ข้อมูลอาจารย์มหาวิทยาลัยเกษตรศาสตร์

ชื่อ นายกาญจนพันธุ์ สุขวิชชัย	
ตำแหน่งทางวิชาการ รองศาสตราจารย์	**สังกัด** ภาควิชาวิศวกรรมไฟฟ้า คณะวิศวกรรมศาสตร์

การดำรงตำแหน่งบริหาร
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การศึกษา Doctor of Engineering (Mechatronics), Asian Institute of Technology, ไทย, 2557

สาขาเชี่ยวชาญ/สนใจ Robotic, Control, AI, Computer System, Embedded System

งานสอน

3D Product Design and Prototyping
Advanced Research Methodology in Electrical Engineerin
App. Artificial Neural Networks & Fuzzy Logic
Applied Artificial Neural Networks and Fuzzy Logic
Applied Neural Network and Fuzzy Logic
Artificial Intelligence System for Robots
Electrical Engineering Laboratory I
Electrical Engineering Project I
Electrical Engineering Project II
Embedded Control Systems
Introduction to Dynamic Control
Introduction to Robotic Systems
Microprocessor
Microprocessor Laboratory
Nonlinear Control Systems
Process Control Laboratory
Real-Time Computer Control
Research Methodology in Electrical Engineering II
Select Topic Ctrl & Measure Engine
Selected Topics in Electrical Engineering
Seminar
ปฏิบัติการวิศวกรรมไฟฟ้า
ไมโครโปรเซสเซอร์

โครงการวิจัย

ปี 2551   โครงการวิจัยพัฒนาเครื่องผลิตแผ่นพิมพ์ลายวงจรต้นแบบหนึ่งหน้า แบบอัตโนมัติ (หัวหน้าโครงการ) ได้รับทุนจากคณะวิศวกรรมศาสตร์ มหาวิทยาลัยเกษตรศาสตร์

ปี 2551   โครงการวิจัยพัฒนาต้นแบบหุ่นยนต์สำรวจอาคารและกำจัดปลวก (หัวหน้าโครงการ) ได้รับทุนจากกรมยุทธโยธาทหารบก กระทรวงกลาโหม

ปี 2559-2560   โครงการพัฒนา ระบบหุ่นยนต์เตะฟุตบอลขนาดเล็ก เพื่อการศึกษา (หัวหน้าโครงการ) ได้รับทุนจากทุนพัฒนาผลิตภัณฑ์นวัตกรรม

บทความวิจัยในวารสารวิชาการ

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บทความวิจัยในการประชุมวิชาการ

ข้อมูลอาจารย์มหาวิทยาลัยเกษตรศาสตร์

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ชื่อ นายกาญจนพันธุ์ สุขวิชชัย	
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อนุสิทธิบัตร

- อนุสิทธิบัตรงานวิจัย ปี 2563 เรื่อง "หุ่นยนต์ดำน้ำ" จาก กรมทรัพย์สินทางปัญญา

- อนุสิทธิบัตรงานวิจัย ปี 2563 เรื่อง "หุ่นยนต์เตะฟุตบอล" จาก กรมทรัพย์สินทางปัญญา

รางวัลผลงานนำเสนอในการประชุมวิชาการ

- Best Paper Award ประจำปี 2559 เรื่อง "Optimal Robust Controller for a BallRiding Robot" จาก The Institute of Electronics and Information Engineers (IEIE), Korea
The Institute of Electronics, Information and Communication Engineers (IEICE), Japan
The Electrical Engineering / Electronics, Computer, Telecommunications and Information Association, Thailand

- Best Paper Award Bronze Prize ประจำปี 2559 เรื่อง "Design of a Fuzzy Logic Adaptive Optimal Robust Controller for a BallRiding Robot" จาก The Institute of Electronics and Information Engineers (IEIE) & IEEE

- Best Paper Award ประจำปี 2560 เรื่อง "Design of the Multitasks Multiprocessors System for an Underwater Robot" จาก มหาวิทยาลัยเกษตรศาสตร์, มหาวิทยาลัยธรรมศาสตร์ (SIIT), Tokyo Institute of Technology (ญี่ปุ่น), สวทช และ IEEE Thailand Section

- Best Paper Award ประจำปี 2561 เรื่อง "Hidden Dot Patterns Recognition using CNNs on Raspberry Pi Zero W" จาก Thai Embedded Systems Association (TESA), Tokyo Institute of Technology (Japan), Faculty of Engineering in cooperation with Embedded System R&D Group Khon Kaen University, Sirindhorn International Institute of Technology Thammasat University, Rajabhat Mahasarakham University, Kasetsart University

- Best Paper Award Control and Robotic ประจำปี 2565 เรื่อง "Investigate GPS Signal Loss Handling Strategies for a Low Cost MultiGPS system based Kalman Filter" จาก ECTI, IEEE

- Best Paper Award ประจำปี 2566 เรื่อง "Implementation of a Monocular ORB SLAM for an Indoor Agricultural Drone" จาก IEEE, ECTI, IAIT, TRS, IEEE-CSST

ผลงานวิจัยนี้เป็นรายการรวบรวมระหว่างปี 1 มกราคม 2551 - 27 เมษายน 2567